

Measurement of flow velocity by magnetic resonance imaging using 2D phase contrast technique: estimation of oblique flow

Soichi AKATA¹, Ammar DARKANZANNLI², Arthur. F. GMITRO²,
Evan C. UNGER², M. Paul CAPP², Kimihiko ABE¹

¹Department of Radiology, Tokyo Medical University

²Department of Radiology, University of Arizona and University Medical Center

ABSTRACT

This study analyzed the effects of the obliqueness of flow on the accuracy of measuring flow velocity by means of the 2D phase contrast MR technique. A constant flow phantom consisting of a pump, a polyethylene tube and a flow meter was assembled. A commercial 1.5 Tesla MR imager was used to perform flow velocity measurements. The phase contrast technique was used to estimate the flow velocity of saline through the phantom. The effects of changes in obliqueness of flow to the plane of imaging were studied. The obliqueness had a significant effect that was more pronounced with increasing section thickness. An increase in the obliqueness angle caused underestimation of the average and maximum velocities. The obliqueness was found to be an important parameter affecting the estimation with the 2D phase contrast MR technique.

The application of MR to flow velocity measurement was first described by Singer¹). Various pulse sequences have been proposed to evaluate the flow velocity by MR. The two main classes of techniques are the time-of-flight method and the phase contrast method. The time-of-flight technique derives its contrast from the flow-related enhancement of inflowing blood^{1~10}). The phase contrast method, on the other hand, is based on applying balanced gradient pulses, and derives its contrast by detecting spin phase differences as blood moves across a magnetic field gradient²). The phase contrast technique is not only a simple subtraction of phase images on a pixel by pixel basis but a complex difference of phase obtained with a known different flow encoding gradient. Phase images are collected using balanced gradient pulses to produce a phase shift for moving spins. The difference in phase is directly proportional to the flow velocity of the spins within the corresponding voxels^{11~15}).

The phase contrast technique is generally better than the time-of-flight technique for quantitative measurement of flow velocity in cardiovascular and cerebrospinal abnormalities^{16~19}). Advantages of the phase contrast method include bi-directional flow sensitivity, ability to obtain both a conventional magnitude image and a velocity image from the same data set¹⁰) and the relative simplicity in interpretation, processing, and display¹⁵).

Cardiac gating can be used in conjunction with phase contrast to provide flow velocity encoded phase images at equally spaced temporal intervals during the cardiac cycle. Interpretation of flow velocity values during the cycle can provide instantaneous average and maximum flow velocity information²⁰).

The purpose of this study is to evaluate the effects of obliqueness of the flow on the accuracy

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Reprint requests to : Soichi AKATA, Department of Radiology, Tokyo Medical University,
6-7-1, Nishi-Shinjuku Shinjuku-ku, Tokyo, 160-0023

of the MR flow velocity measurement.

MATERIALS AND METHODS

Flow Phantom;

We studied flow velocity of saline in a polyethylene tube with an inside diameter of 6.4 mm; inside area of 0.32 cm². The tube was connected in a loop with a fluid supply reservoir. Two sections of the tubing, one with outflow fluid and the other with return flow, were embedded in the center of a 10% agar-gel container (25 cm length, 17 cm width, 10 cm height). The phantom was placed in the MR imager with the direction of flow parallel to the static magnetic field vector (i.e.; along the z axis).

The constant flow was driven by a pump (BIO-CONSOLE_{TM}; VIO-MEDICUS, INC., Minnetonka, MN, USA). The pump was placed outside the magnet room to minimize an interaction between pump and magnet, and to reduce radio frequency interference²¹. The fluid used was saline with a T1 relaxation time of approximately 4065 msec.

Imaging Setup;

The flow phantom was placed in a 1.5 Tesla clinical MR imager, GE Signa (General Electric Medical Systems, Milwaukee, WI, USA). The two-dimensional (2D) phase contrast technique using balanced gradient pulses was used to measure the flow velocity of the fluid. Measurements were performed using a circular surface coil with a diameter of 12 cm. A field of view of 16 cm was used, and the slice thickness was 10 mm. The imaging parameters used were repetition time (TR) = 50 msec, echo time (TE) = 12.1 msec, the flip angle was 300, the matrix size was 256 × 256, and number of acquisition was one. We confirmed the accuracy of 2D phase contrast MR flow velocity measurement by using a flow meter, and then began the study to test the impact of changing the obliqueness of flow.

The effect of oblique flow was studied in two different slice thicknesses (3 mm and 10 mm) by changing the tube angle to the imaging plane in steps of 10° up to 80°. We made 28.6 cm/sec average flow velocity by a pump and 70.0 cm/sec VENC (velocity encoding) value were used. We evaluated the maximum flow velocity in this study due to difficulty in cre-

ation of an elliptic ROI. Maximum flow velocity was obtained by determining the pixel with the maximum flow velocity within the tube area. We measured the maximum flow velocity components along the X, Y, and Z axes, and calculated the MR measured maximum flow velocity ($V_{(MR)}$) through the following equation (1),

$$V_{(MR)} = \sqrt{V_{X(MR)}^2 + V_{Y(MR)}^2 + V_{Z(MR)}^2} \quad (1)$$

where $V_{X(MR)}$, $V_{Y(MR)}$ and $V_{Z(MR)}$ are the MR measured maximum flow velocity components in the X, Y, and Z directions, respectively. When the flow direction was angled from the Z axis (slice selection direction, which is normal to the slice plane) towards the X axis (frequency encoding direction) in the X-Z plane, the relationship between the true maximum flow velocities and the true maximum flow velocity components along the X axis and the Z axis are

$$V_X = V \sin q, \quad (2)$$

$$V_Z = V \cos q, \quad (3)$$

where q is angle between the flow direction and the slice selection direction, and V_X , V_Z , and V are the true maximum flow velocity components along the X axis, the Z axis, and true maximum flow velocity, respectively.

We compared the true maximum flow velocity with the MR measured maximum flow velocity from the MR measured maximum flow velocity components according to equation (1), and we also compared the MR measured maximum flow velocity components along the X and Z axes with the calculated true maximum flow velocity components according to equation (2) and (3). As a function of obliqueness, the “true” maximum flow velocity was defined as the MR measured maximum flow velocity at $q = 0$.

RESULTS

Obliqueness of the flow to the imaging plane had a significant effect on the accuracy of flow velocity measurement with 2D phase contrast. As shown in Fig-1a and 1b, an increase in the oblique angle caused underestimation of the maximum flow velocities. The obliqueness

effect was more pronounced when the slice thickness was increased from 3 mm to 10 mm. As the angle of obliqueness increased from 0° to 80° , measurements of maximum flow velocities decreased from 54.4 cm/sec to 34.9 cm/sec for 10 mm slices, and from 54.7 cm/sec to 42.1 cm/sec for 3 mm slices.

Errors in flow velocity measurements were primarily observed along the frequency encoding direction (X axis) (Fig. 1a, b). MR measurements of the maximum flow velocity along the slice selection direction (Z axis) correlated well with the maximum flow velocity component along the Z axis calculated by equation (3). The agreement between the MR measured maximum flow velocities and true maximum flow velocities was good up to oblique angles of 60° for 3 mm slice thickness and 40° for 10 mm slice thickness. Although virtually zero flow velocity was detected in the Y direction since the tube was rotated in the X-Z plane about the Y axis, actually the MR measured maximum flow velocity in the Y direction became around 2 cm/sec because of noise of a background.

DISCUSSION

Phase contrast flow velocity measurement is limited, because the spine phase is cyclic and there is a natural limit of 2 radians to the maximum range of phase that can be measured²²⁾. The range of flow velocities that can be measured by the phase contrast technique covers the complete physiological range from approximately 0.1 mm/sec²³⁾ to 500 cm/sec²⁴⁾.

The MR phase contrast technique is sensitive to flow both within and perpendicular to the imaging plane²⁵⁾, but flow-induced phase shift occurs only in the direction of the applied balanced gradient pulse²⁰⁾. Although it is possible to measure the flow velocity components in all three orthogonal directions (X, Y and Z axes), flow velocity in the oblique directions cannot be measured directly by our MR equipment. So we had to use equation (1) to calculate the velocities of flow oblique to the imaging plane.

We compared the true maximum flow velocity and the true maximum flow velocity components along X (frequency encoding direction) and Z (slice selection direction) axes with the calculated MR measured maximum flow velocity and the MR measured maximum flow velocity

components along X and Z axes. As a function of the angle of the "true" maximum flow velocity was defined as the MR measured maximum flow velocity components were calculated by equations (2) and (3). True and MR measured maximum flow velocity component along the Z axis (V_Z and $V_{Z(MR)}$) were the same up to 80° obliqueness, and the true and MR measured maximum velocities also correlated well, regardless of the slice thickness, however, true maximum flow velocity components along the X axis (V_X) was inconsistent with MR measurement ($V_{X(MR)}$) at larger oblique angles (exceeding 40°). The error in MR measured maximum flow velocity component along the X axis increased when the slice thickness increased.

The error is thought to be due to two effects. First, when a 10 mm slice thickness was used, there was a partial volume effect (i.e., phase shifts averaging of moving spins and static spins). When the phase average over a pixel includes a static phase shift due to spins outside the tube, the MR measured flow velocity will be underestimated. The percentage of static spins increases as the angle of obliqueness increases. In slices thinner than the tube diameter, however, there is less partial volume effect (Fig. 2a, b, c). The second reason for underestimation of the flow velocity is that the flow profile is not constant²⁶⁾. The flow near the tube wall is slower than at the center of the tube. The measured flow velocity is calculated by an average of various phase shifts due to different flow values dependent on the flow profile. While this error in measurement is not high even at a very high obliqueness angle (70°), the error was nevertheless present and may account for the error observed in the 3 mm slices (Fig. 3a, b). We have no explanation why only $V_{X(MR)}$ had errors and $V_{Z(MR)}$ correlated with V_Z on both experiments.

In velocity measurements of oblique flow, the angle of obliqueness, the diameters of vessels, and the slice thickness all affect the accuracy of the flow velocity measurement. It is evident that slice thickness should be kept as small as possible to minimize the errors of oblique flow velocity measurement. This is particularly important in tortuous and/or winding vessels where larger obliquity can occur.

It is also possible to reduce the effect of obliqueness in MR imaging by carefully select-

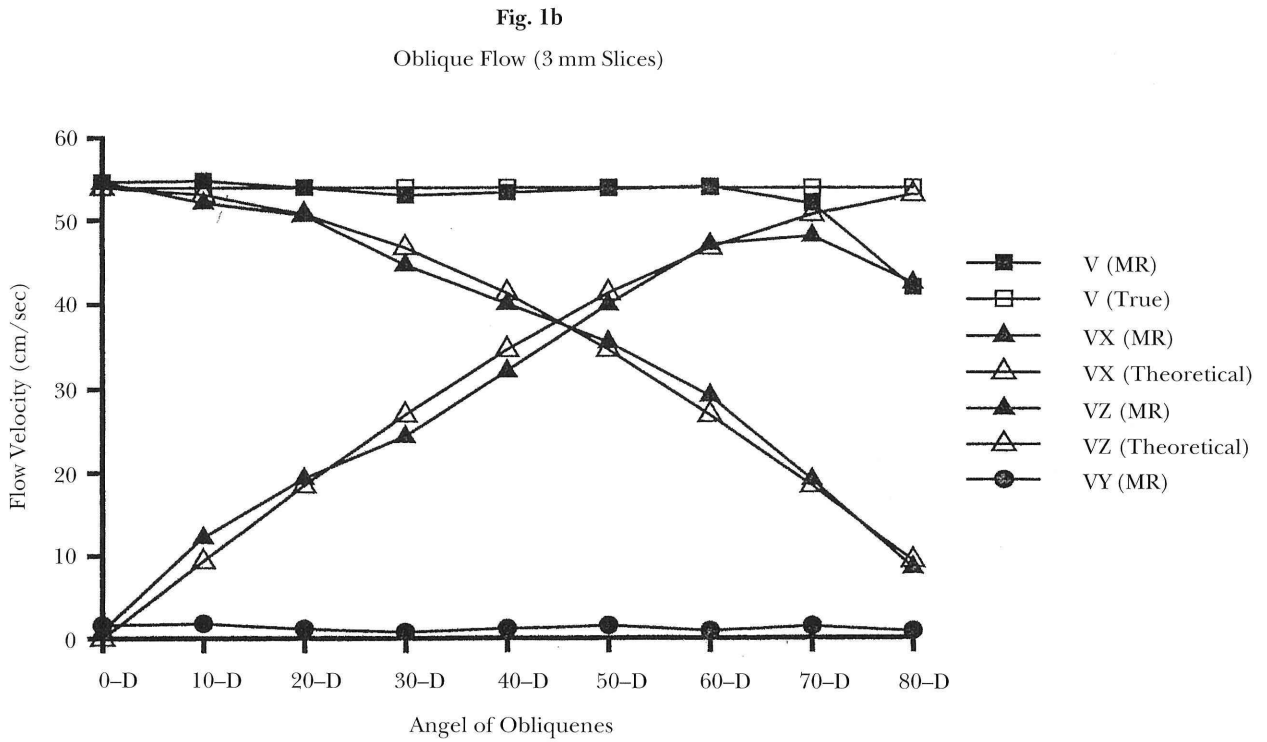
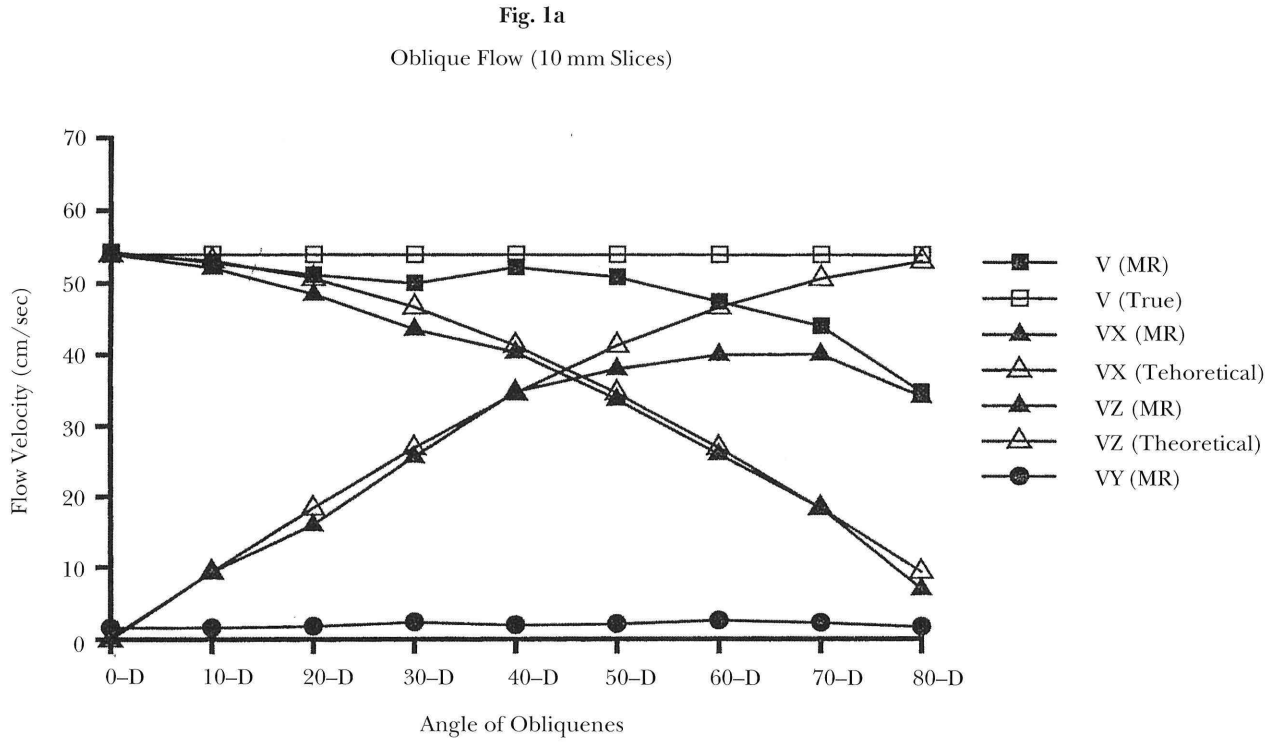


Fig. 1 True maximum velocity along the z axis measured through MR correlates well with actual V_z measurements up to an 80° angle of obliqueness, regardless of slice selection. (a) Results of maximum velocity measurement using 10 mm slice thickness. Errors in measuring V_x are apparent where angle of obliqueness reached 50° . (b) results of maximum velocity measurement using 3 mm slice thickness, error in measuring V_x are apparent when the angle of obliqueness reached 70° .

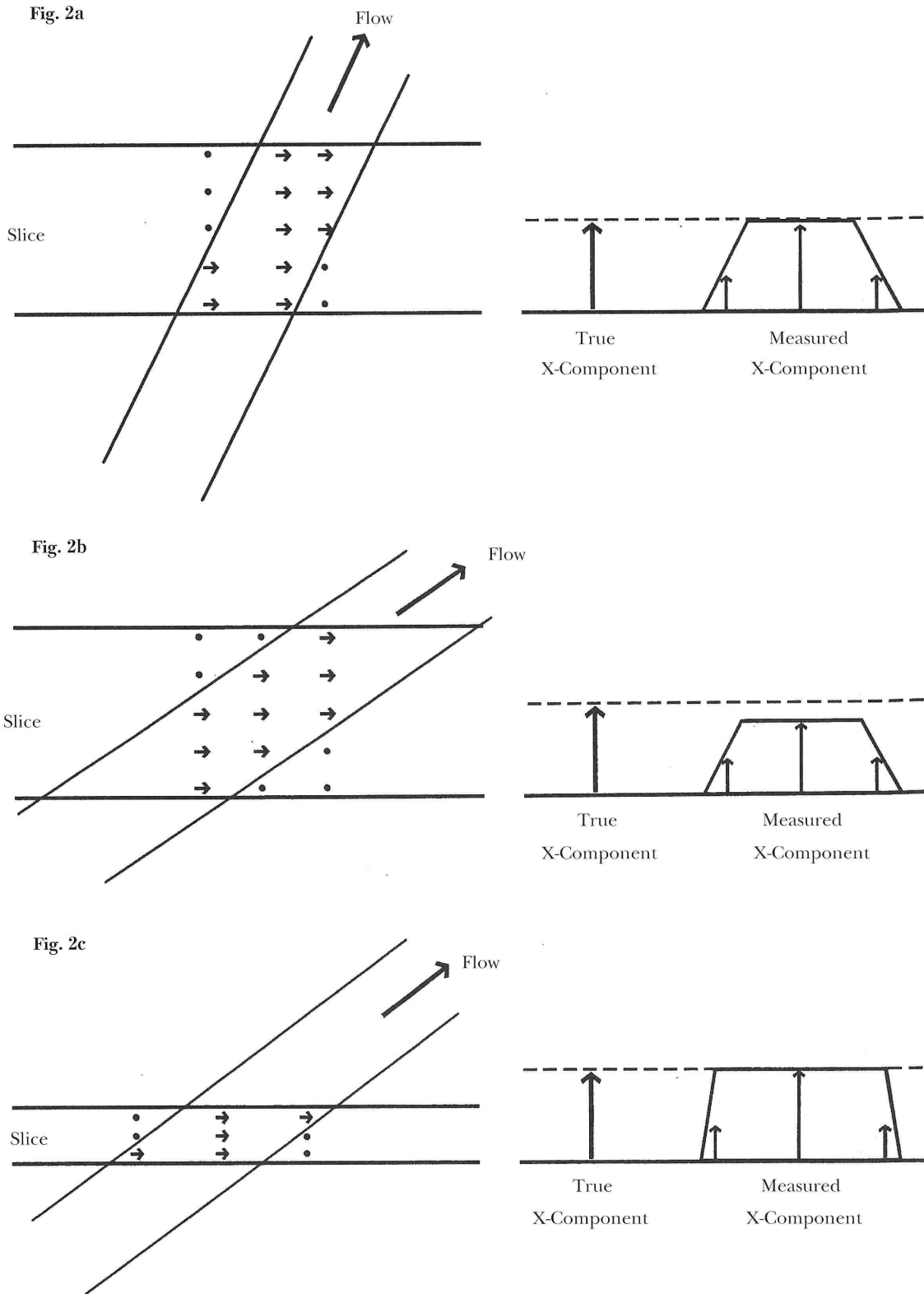


Fig. 2 (a) When a 10 mm slice thickness is used for the oblique flow measurement, there is partial volume effect of static spins (dots) and X component of moving spins (small arrows). When the phase average over a pixel includes a static phase shift due to spins outside the tube, the measured maximum flow velocity will be underestimated. (b) The percentage of static spins increases as the angle of obliqueness increases. In situation (b), Every pixel includes the phase of static spins, so measured maximum X component velocity by MR is not compatible with the true maximum X component velocities. (c) Thinner slice thickness has less error. This explanation accounts for the error in measurement of the Z component velocity.

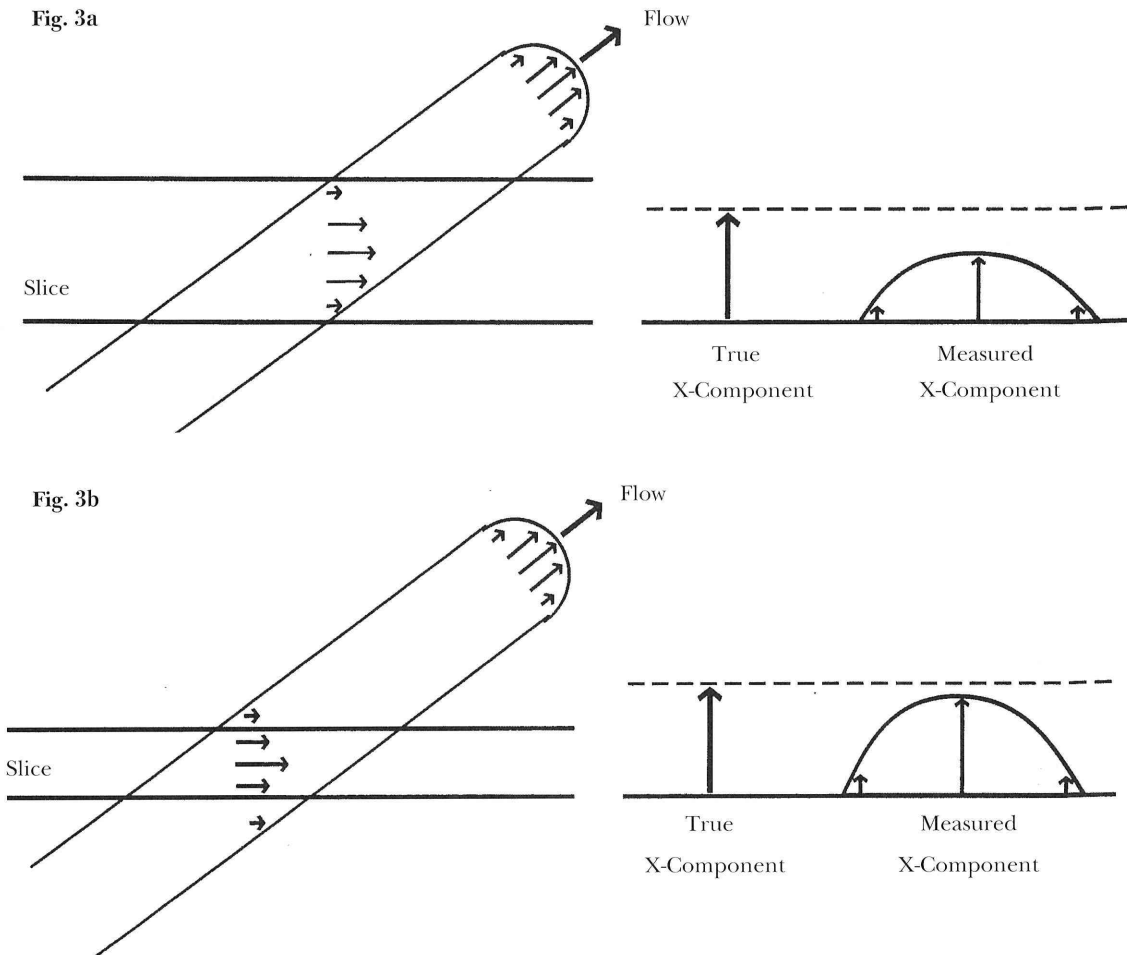


Fig. 3 (a) The flow near the tube wall is slower than at the center of the tube because the flow profile is not constant. The measured velocity is calculated by an average of various phase shifts. (b) While this error in measurement is not high even at a very high obliqueness angle (70°), the error is nevertheless present and may account for the error observed in the 3 mm slices.

ing the imaging plane to be perpendicular to the flow direction. Therefore, it is recommended to obtain a suitable scout image before attempting to measure flow velocity in the vessel of interest.

The phase contrast technique provides the best estimate of MR flow velocity, because it contains only information from moving spins¹⁵⁾ and it is insensitive to most imaging plane has been shown to affect the estimation of flow velocity. The phase contrast technique is sensitive to other artifacts as are most MR techniques to susceptibility, variations in the body surface, inhomogeneity of boundaries of different tissues¹⁴⁾, respiratory and other kinds of patient motion¹⁰⁾ and turbulence by irregular inner face and shapes of vessels²⁷⁾.

Pulsatile flow may affect oblique flow because pulsatile flow predisposes more to tur-

bulence than constant flow. For the purpose of further investigation on the accuracy of MR flow velocity measurement in the human body, we have plans to study obliqueness of vessel orientation in pulsatile flow phantoms and animals to compare MR measurement results to those obtained with conventional Doppler US examinations, and implanted flow meters in animals. Our study of an in vitro system is a useful step for the clinical application of the flow velocity measurement with the 2D phase contrast technique.

CONCLUSION

The spin phase acquired has been linearly proportional to the flow velocity. Obliqueness of vessels to the imaging plane has been shown to be the most important factor in estimation of flow values. To reduce error, slice thickness

should be as thin as possible.

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2次元 phase contrast 法を用いた MR による流速測定法における 撮影面に対する斜め方向の流れがおよぼす測定誤差の評価

赤田壮市¹⁾ Ammar Darkanzanli²⁾ Arthur F. Gimitro²⁾
Evan C. Unger²⁾ M. Paul Capp²⁾ 阿部公彦¹⁾

¹⁾ 東京医科大学放射線科, ²⁾ アリゾナ大学放射線科

【要旨】 phase contrast 法は両極方向に同じ強さの傾斜磁場を作用させることで、遅い静脈血流や脳脊髄液から速い大動脈の流れまで幅広い流速を測定可能であり、また流入および流出両方向の測定も可能である。しかし測定画像断面に対し垂直で無い流れは、その流入角度により誤差を引き起こしていると考えられるが、それを検討した報告はない。そこで測定画像断面に対する液体の流入方向を変化させることにより、引き起こされる測定誤差を評価し検討を行った。

定常流ポンプ、ポリエチレンチューブと流速測定器よりになる実験装置を作成した。1.5TeslaMR装置にて、2次元 phase contrast 法を用いて実験装置内を流れる生理的食塩水の流速を測定した。流れの角度は測定画像断面に対し垂直から、10度ずつ変化させ80度まで測定した。

結果として流入角度は低くなった。またスライス厚が厚い方が誤差は大きかった。従って、2次元 phase contrast 法による流速測定に関し、できる限りスライス厚は薄くし、測定画像断面に対し流入角度が付いた時には、角度に応じた補正が必要である。

キーワード : Phase Contrast 画像, Oblique flow, 磁気共鳴画像, 流速測定.
